

On Self-Adjoint Boundary Value Problems for a Functional Equation of Even Order

Elena Vladimirovna Molchanova Alves^{1*}, Manuel Joaquim Alves² and Sergey Labovskiy³

¹PhD in Physics and Mathematics, Associate Professor of the School of Economy and Business Administration. Higher Institute of Sciences and Technology, Mozambique

²PhD in Physics and Mathematics, Full Professor of the Mathematics and Informatics Department. Eduardo Mondlane University, Mozambique

³PhD in Physics and Mathematics, Associate Professor of Plehanov University of Economy, Russia

ABSTRACT

Investigating a functional differential equation of even order, we explore a class of self-adjoint boundary value problems with two-point conditions. We establish the basis property of the system of eigenfunctions and compare the eigenvalues.

*Corresponding author

Elena Vladimirovna Molchanova Alves, PhD in Physics and Mathematics, Associate Professor of the School of Economy and Business Administration. Higher Institute of Sciences and Technology, Mozambique. ORCID: <https://orcid.org/0009-0000-1452-2553>.

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Problem, Notation

Introduction

As is known, the spectral problem $Lu = \lambda u$ for a differential operator of n th order has a real spectrum and a complete orthogonal system of eigenvectors in the case of a self-adjoint operator and corresponding self-adjoint conditions. In was considered self-adjoint functional differential Sturm-Liouville boundary value problem [1,2]

$$-(pu')' + \int_0^l u(s) d_s r(x, s) = \rho f,$$

$$(pu')|_{x=0} = 0, \quad ku(l) + pu'|_{x=l} = 0$$

($\rho(x)$ is a positive weight function). It can be considered as a generalization of the Sturm-Liouville boundary value problem for a string, the system of its eigen functions forms an orthogonal basis in two spaces. In were considered generalizations for equations of even order [3,4]

$$(-1)^m u^{(2m)} - \int_0^l u(s) q(x, ds) = \rho f, \quad x \in [0, l] \quad (m \geq 1).$$

with boundary conditions

$$u^{(k)}(0) = 0, \quad k = 0, \dots, m-1,$$

$$u^{(k)}(l) = 0, \quad k = m, \dots, 2m-1.$$

These conditions are a special case of the boundary conditions considered in [5] and [6]. Usually such a boundary value problem is called focal [7]. A boundary value problem with periodic boundary conditions is also self-adjoint [8]. These problems are regular, the spectrum of such operators is real and discrete, the eigenfunctions are orthogonal and form a basis in the corresponding spaces. Taking this opportunity, we note that in for the singular operator [9]

$$\frac{1}{\rho(x)} (-1)^m (p(x)u^{(m)})^{(m)}, \quad x \in [0, \infty)$$

necessary and sufficient conditions for the discreteness of the spectrum are obtained.

This paper describes a class of two-point boundary conditions under which the boundary value problem operator remains self-adjoint (self-adjoint extension). For any such problem, the above properties remain the same. We consider the operator (symbol ‘:=’ is read as is equal by definition)

$$\mathcal{L}u(x) := \frac{1}{\rho(x)} \left((-1)^m u^{(2m)} + \int_0^l u(s) r(x, ds) \right),$$

$$x \in [0, l] \quad (m \geq 1). \quad (1.1)$$

Assumptions regarding the function $r(x, ds)$ are given below. We write the boundary conditions in the form

$$B_S u = 0, \quad (1.2)$$

where the operator of boundary conditions B_S is defined in section of notations in (1.7).

Notations and assumptions

The integral in (1.1) is the Stieltjes integral, instead of $r(x, ds)$ it can be written $dsr(x, s)$. In the case of $r(x, ds)$, the function $r(x, \cdot)$ is considered as a charge (depending on the parameter x). If the charge is discrete

$$\int_0^l u(s)r(x, ds) = \sum_{i=1}^{\infty} r_i(x)u(h_i(x)),$$

we obtain an equation with a deviating argument. Let us introduce the following definitions and assumptions.

- ‘:=’ means equal by definition, $\Delta := [0, l]$, \equiv means is equivalent for measurable functions.
- $L_2(\Delta, \rho)$ is the space of functions whose square is Lebesgue integrable with positive and measurable weight $\rho(x)$ on Δ and scalar product

$$(f, g) := \int_{\Delta} f(x)g(x)\rho(x) dx, \quad (1.3)$$

$L_2(\Delta) := L_2(\Delta, 1)$. We assume that $\int_{\Delta} \rho(x) dx < \infty$ (regularity condition).

- For almost all $x \in \Delta$, the function $r(x, \cdot)$ has limited variation on Δ , for any $s \in \Delta$ function $r(\cdot, s)$ measurable on Δ , $r(x, 0) = 0$; total variation $|r|(x) := \text{var}_{s \in \Delta} r(x, s)$ is Lebesgue integrable. It is known that $r = r_+ - r_-$, where r_+ and r_- are non-decreasable functions, and $|r|(x) = r_+(x, l) + r_-(x, l)$, $r_+(x, 0) = r_-(x, 0) = 0$.

$$\text{Let } \xi_+(x, y) := \int_0^x r_+(s, y) ds, \quad \xi_-(x, y) := \int_0^x r_-(s, y) ds, \quad \xi = \xi_+ - \xi_-.$$

Assume that ξ is symmetrical $\xi(y, x) = \xi(x, y)$. Then ξ_+ and ξ_- are symmetrical.

- AC^k ($k \geq 0$) is the set of functions u , that have absolutely continuous on Δ derivative $u^{(k)}$, $u^{(0)} := u$.

- $[u, v]$ is bilinear form defined on AC^{m-1} by equality

$$[u, v] := \int_{\Delta} u^{(m)}v^{(m)} dx + \int_{\Delta} v(x) dx \int_{\Delta} u(s)dsr(x, s).$$

The symmetry of the function ξ implies the symmetry of $[u, v]$, since by Lemma 3.12

$$[u, v] = \int_{\Delta} u^{(m)}v^{(m)} dx + \int_{\Delta \times \Delta} u(s)v(x)d\xi. \quad (1.4)$$

Assume that $[u, u] > 0$ if $u \neq 0$. To do this we require that

$$\int_{\Delta \times \Delta} u(s)u(x)d\xi > 0 \quad (1.5)$$

if $u \neq 0$.

- W is Hilbert space (Lemma 3.1) of functions from AC^{m-1} satisfying $[u, u] < \infty$, with scalar product $[u, v]$.
- W_S : Let the index sets $I, J \subset \{0, 1, \dots, m-1\}$ be arbitrary, $S = (I, J)$ and

$$W_S = \{u \in W : u^{(i)}(0) = 0, \forall i \in I, u^{(j)}(l) = 0, \forall j \in J\}. \quad (1.6)$$

Obviously, W_S is a (closed) subspace of W . In particular, $W = W_S$ if $S = (\emptyset, \emptyset)$. On W_S we will consider the form $[u, v]$ defined by the equality

- $T : W \rightarrow L_2(\Delta, \rho)$ is the (set-theoretic embedding) operator defined by the equality

$$Tu(x) := u(x), \quad x \in \Delta.$$

The definition is correct and T is continuous (Lemma 3.2).

- T^* is the adjoint operator to T ($T^* : L_2(\Delta, \rho) \rightarrow W$), T^* is the adjoint operator to T ($T^* : L_2(\Delta, \rho) \rightarrow W_S$).

- Operator $B_S : AC^{2m-1} \rightarrow R^{2m}$ is linear operator of boundary conditions. Define for $S = (I, J)$ the index sets

$$U := \{2m-1-i : i \notin I, i \in \{0, 1, \dots, m-1\}\}, \\ V := \{2m-1-i : i \notin J, i \in \{0, 1, \dots, m-1\}\}.$$

We use all these indices to form the boundary conditions operator:

$$B_S u := (u^{(i)}(0) : i \in I \cup U, u^{(k)}(l) : k \in J \cup V). \quad (1.7)$$

For example, if $m = 3$, $I = \{0, 2\}$, $J = \{2\}$, then $S = (0, 2; 2)$, $U = \{4\}$, $V = \{4, 5\}$,

$$B_S u = (u(0), u''(0), u^{(4)}(0), u''(l), u^{(4)}(l), u^{(5)}(l)).$$

G_S is the Green's operator of the boundary value problem $Lu = f, B_S u = 0$, that is, $u = G_S f$, if the problem is uniquely solvable.

The Green's operator G_S has an integral representation (see, for example, [4])

$$u(x) = \int_0^l G_S(x, s)f(s)\rho(s) ds,$$

The Green's function $G_S(x, s)$ is symmetric i.e. $G_S(x, s) = G_S(s, x)$. For each s , the section $G_S(\cdot, s)$ is a solution to the problem $Lu = 0, B_S u = 0$ (but a jump in the $(2m-1)$ th derivative is allowed).

Remark 1.1. A special case of the form $[u, v]$ is the obviously positive form defined by the bilinear form ($q \geq \neq 0, \xi_1 \geq 0$)

$$[u, v] = \int_{\Delta} u^{(m)}v^{(m)} dx + \int_{\Delta} q(x)u(x)v(x) dx + \frac{1}{2} \int_{\Delta \times \Delta} (u(x) - u(s))(v(x) - v(s))d\xi_1. \quad (1.8)$$

It can be represented in the form

$$[u, v] := \int_{\Delta} u^{(m)}v^{(m)} dx + \int_{\Delta} R(x)u(x)v(x) dx - \int_{\Delta} v(x) dx \int_{\Delta} u(s)dsr_1(x, s).$$

$$R(x) \geq r_1(x), \quad r_1(x) := r_1(x, l) - r_1(x, 0) = r_1(x, \Delta), \text{ and} \\ \int_{\Delta} (R(x) - r_1(x)) dx > 0.$$

Investigation of the Spectral Problem

We follow the scheme in [3]. The difference is that we will consider the form $[u, v]$ in two spaces: in W and its closed subspace W_S , considered as an independent Hilbert space. Therefore, what is given below for W is also true for W_S .

Minimizing the functional $(1/2)[u, u] - (f, Tu), u \in W$

leads to an equation in variational form

$$[u, v] = (f, Tv), \quad \forall v \in W, \quad f \in L_2(\Delta, \rho). \quad (2.1)$$

The operator T is bounded (Lemma 3.2), so the functional $v \mapsto (f, Tv)$ is bounded, and the equation (2.1) has a unique solution $u = T^*f \in W$.

Since the image of $T(W)$ is dense in $L_2(\Delta, \rho)$ (Lemma 3.5), then [8, Lemma 5.1] the adjoint operator T^* is an injection. It follows that the inverse operator

$$\tilde{\mathcal{L}} := (T^*)^{-1} \quad (2.2)$$

is defined on the image $R(T^*) := T^*(L_2(\Delta, \rho))$. Let us denote the domain of Let us denote the domain of definition of the operator $\tilde{\mathcal{L}}$ by $D(\tilde{\mathcal{L}}) := R(T^*)$. The spectrum of the operator $\tilde{\mathcal{L}}$ is determined by the spectral problem $\tilde{\mathcal{L}}u = \lambda Tu$, i.e. by esolvent $(\tilde{\mathcal{L}} - \lambda T)^{-1}$. This problem is equivalent to $u = \lambda T^*Tu$. The

operators T and T^* are compact (Lemma 3.6), therefore the spectrum of the operator $\tilde{\mathcal{L}}$; discrete, real and positive. The above is also true for the restriction of the form $[u, v]$ to the subspace W_S .

We denote the corresponding L operator by $\tilde{\mathcal{L}}_S := (T_S^*)^{-1}$.

It should be noted that the operators T^* and T_S^* are different because they are associated with T defined in different domains W and W_S .

Theorem 2.1. *The spectral problem $\tilde{\mathcal{L}}_S u = \lambda Tu$ has a complete and orthogonal system of eigenfunctions in W_S (as well as in $L_2(\Delta, \rho)$):*

$\tilde{\mathcal{L}}_S u_k = \lambda_k T u_k, k = 0, 1, 2, \dots$ *The eigenvalues are positive and have a single condensation point $+\infty$, i.e. $0 < \lambda_0 \leq \lambda_1 \leq \dots$, and $\lambda_k \rightarrow \infty$. For λ different from the eigenvalues, the equation $e Lu - \lambda T_u = f$ has a unique solution in W_S for any $f \in L_2(\Delta, \rho)$.*

As follows from the statement below, the operator L defined by

the equality (1.1) gives a representation of the operator $\tilde{\mathcal{L}}_S$

defined on the set W_S .

Theorem 2.2. The operator defined by the equality (2.2) in the

domain $D(\tilde{\mathcal{L}}_S) := R(T_S^*) \subset W_S$ coincides with the operator \mathcal{L}

defined by the equality (1.1). Equation

$$(-1)^m u^{(2m)} + \int_0^l u(s)r(x, ds) = \rho f, \quad x \in [0, l] \quad (2.3)$$

is equivalent on $D(\tilde{\mathcal{L}}_S)$ to equation (2.1).

Proof. It follows from Lemma 3.10.

Corollary 2.1. Boundary value problem (2.3), $B_S u = 0$ is uniquely solvable in $D(\tilde{\mathcal{L}}_S)$ for any $f \in L_2(\Delta, \rho)$.

Remark 2.1. The form (1.8) corresponds to the functional differential operator

$$\mathcal{L}_1 u(x) := \frac{1}{\rho(x)} \left((-1)^m u^{(2m)} + R(x)u - \int_0^l u(s)r_1(x, ds) \right), \quad x \in [0, l]. \quad (2.4)$$

If we consider the equation

$$[u, v] = (f, Tv), \quad u \in W, \quad \forall v \in W_S, \quad (2.5)$$

then in a wider space W one can obtain nonzero solutions to the homogeneous equation $Lu = 0$. In W_S this equation has a unique

solution $u_0 = T_S^* f$. Let e_1, \dots, e_n be a basis in the orthogonal

complement of W_S^\perp . Here n is the total number of elements of the sets I and J , where $S = (I, J)$. Then the general solution to the equation (2.5) has the form

$$u = T_S^* f + \sum_{k=1}^n c_k e_k.$$

The orthogonal complement of W_S^\perp is the null space of L , i.e. $Le_k = 0, k = 1, \dots, n$.

Let us note an important estimate for the first eigenvalue (depending on S)

$$\lambda_0 = \inf_{u \in W_S, u \neq 0} \frac{[u, u]}{(Tu, Tu)} = \inf_{u \in W_S, u \neq 0} \frac{[u, u]}{\int_{\Delta} u^2 \rho dx}. \quad (2.6)$$

From this estimate we obtain a comparison of the first eigenvalue for different boundary conditions. Let $S_1 = (I_1, J_1), S_2 = (I_2, J_2)$, and $\lambda_{01}, \lambda_{02}$ be the corresponding first eigenvalues. If $I_1 \subset I_2, J_1 \subset J_2$, then

$$\lambda_{01} \leq \lambda_{02}.$$

Auxiliary Lemmas. Properties of Space and Operators
Space W . Boundedness and compactness of T

Lemma 3.1. *The space W with scalar product $[u, v]$ is Hilbert.*

Proof: We need to show that every fundamental sequence u_n in W converges (in W). Let us represent $u_n(x)$ as the sum $u_{0n}(x) + p_n(x)$, where

$$u_{0n}(x) = \int_0^x \frac{(x-s)^{m-1}}{(m-1)!} u_n^{(m)}(s) ds,$$

and $p_n(x)$ is polynomial of degree at most $m-1$. From (1.4) it follows that $u_n^{(m)}$ is fundamental in $L_2(\Delta)$. Therefore $u_n^{(m)} \rightarrow \varphi \in L_2(\Delta)$.

This implies convergence

$$u_{0n}(x) \rightarrow \int_0^x \frac{(x-s)^{m-1}}{(m-1)!} \varphi(s) ds.$$

This convergence is not only uniform, but also in W . The sequence p_n is fundamental in W . Due to the condition (1.5) p_n converges on a set of positive measure. But p_n is a polynomial of degree at most $m-1$, so p_n converges in the sense of W .

Lemma 3.2. *The operator T acts from W to $L_2(\Delta, \rho)$ and is bounded.*

Proof: The statement follows from the estimate

$$\begin{aligned} (Tu, Tu) &= \int_0^l \left(\int_0^x \frac{(x-s)^{m-1}}{(m-1)!} u^{(m)}(s) ds \right)^2 \rho(x) dx \\ &\leq \int_0^l \rho(x) dx \int_0^x \left(\frac{(x-s)^{m-1}}{(m-1)!} \right)^2 ds \int_0^x (u^{(m)}(s))^2 ds \\ &\leq [u, u] \int_0^l \rho(x) dx \int_0^x \left(\frac{(x-s)^{m-1}}{(m-1)!} \right)^2 ds. \end{aligned}$$

The next two lemmas have an auxiliary role.

Lemma 3.3. *Let $\int_{\Delta} f(x)h(x) dx = 0$ for any $h \in L_2(\Delta)$*

such that

$$\int_{\Delta} (c_1 + c_2x + \dots + c_mx^{m-1})h(x) dx = 0 \quad (\forall c_1, \dots, c_m). \tag{3.1}$$

Then $\exists c_1, \dots, c_m$ such that

$$f(x) = c_1 + c_2x + \dots + c_mx^{m-1}.$$

Lemma 3.4. $\int_{\Delta} f(x)v^{(m)}(x) dx = 0$ for any $v \in AC^{m-1}$

such that $v^{(m)} \in L_2(\Delta)$, and satisfying the equalities

$$v(0) = \dots = v^{(m-1)}(0) = v(l) = \dots = v^{(m-1)}(l) = 0. \tag{3.2}$$

Then $\exists c_1, \dots, c_m$ such that

$$f(x) = c_1 + c_2x + \dots + c_mx^{m-1}.$$

Proof: We use Lemma 3.3. Any h satisfying the condition (3.1) can be represented as $h = v^{(m)}$, where v satisfies the conditions of our lemma. Indeed, as such a function we need to take

$$v(x) := \int_0^x \frac{(x-s)^{m-1}}{(m-1)!} h(s) ds.$$

From (3.1) it follows (3.2).

Since $\int_{\Delta} f(x)h(x) dx = \int_{\Delta} f(x)v^{(m)}(x) dx = 0$, the statement of our lemma follows from Lemma 3.3.

Lemma 3.5. The images $T(W_S)$ and $T(W)$ are dense in $L_2(\Delta, \rho)$.

Proof: It is enough to consider $T(W_S)$. Suppose that the closure $T(W_S)$ does not coincide with $L_2(\Delta, \rho)$. Then there exists $h \in L_2(\Delta, \rho)$ orthogonal to $T(W_S)$, i.e.

$$(\forall u \in W_S) \int_0^l h(x)u(x)\rho(x) dx = 0.$$

Using the integration by parts

$$\int_0^l hu\rho dx = \sum_{k=1}^m (-1)^{k-1} H^{(m-k)} u^{(k-1)} \Big|_0^l + (-1)^m \int_0^l H(x)u^{(m)}(x) dx,$$

where $H^{(m)} = h\rho$. We will assume that u satisfies (3.2). Then

$$0 = \int_0^l H(x)u^{(m)}(x) dx.$$

From Lemma 3.4 $H = c_1 + c_2x + \dots + c_mx^{m-1}$. Therefore

$$h = H^{(m)}/\rho \equiv 0.$$

Lemma 3.6. The operator T is compact.

Proof: We refer, for example, to the work [3], which establishes (very simply, by the way) compactness for a form containing

only the term $\int_{\Delta} u^{(m)}v^{(m)} dx$. This will also imply compactness in the case of the form (1.4). There is a difference due to the boundary conditions, but they are finite-dimensional and do not affect compactness.

Euler's equation

The next two statements are obtained by integration by parts.

Lemma 3.7. Let $u^{(2m-1)}$ be absolutely continuous. Then

$$\int_0^l u^{(m)}v^{(m)} dx = \sum_{i=1}^m (-1)^{i-1} u^{(m+i-1)}v^{(m-i)} \Big|_0^l + (-1)^m \int_0^l u^{(2m)}v dx. \tag{3.3}$$

Lemma 3.8. Let φ be Lebesgue integrable on $[0, l]$ and let the function v have an absolutely continuous derivative of order $m-1$. Then

$$\int_0^l \varphi v dx = \sum_{i=0}^{m-1} (-1)^i F^{(m-1-i)}v^{(i)} \Big|_0^l + (-1)^m \int_0^l F(x)v^{(m)} dx, \tag{3.4}$$

where $F^{(m)} = \varphi$.

Lemma 3.9. Let $f \in L_2(\Delta, \rho)$, $u, v \in W$,

$$\int_{\Delta} u^{(m)}v^{(m)} dx + \int_{\Delta} v(x) dx \int_{\Delta} u(s) d_s r(x, s) = \int_{\Delta} f v \rho dx. \tag{3.5}$$

Then

$$\int_{\Delta} (u^{(m)} - (-1)^m F) v^{(m)} dx = \sum_{i=0}^{m-1} (-1)^i F^{(m-1-i)}v^{(i)} \Big|_0^l, \tag{3.6}$$

where $\varphi := -\int_{\Delta} u(s) d_s r(\cdot, s) + f\rho$.

Proof: The product $f\rho$ is integrable on Δ , since

$$\left(\int_0^l f\rho dx \right)^2 \leq \int_0^l f^2 \rho dx \int_0^l \rho dx.$$

The equation (3.5) will take the form

$$\int_{\Delta} u^{(m)}v^{(m)} dx = \int_{\Delta} \varphi v dx. \tag{3.7}$$

Substituting (3.4) into (3.7) we get (3.6).

The equality (3.6) can be simplified if we choose a function F that satisfies, for example, the conditions $F(0) = \dots = F^{(m-1)}(0) = 0$. However, this is not necessary for our purpose.

Lemma 3.10 (Euler's equation). Let $f \in L_2(\Delta, \rho)$, and the function $u \in W_S$ be a solution to (3.5) for any $v \in W_S$.

Then $u \in AC^{2m-1}$ is a solution to the equation $Lu = f$, where L is defined by the equality (1.1), and satisfies the boundary conditions (1.2).

Proof: Function u satisfies (3.6), W_S contains the set specified in lemma 3.4, so from (3.6), (3.2)

$$u^{(m)} - (-1)^m F = c_1 + c_2 x + \dots + c_m x^{m-1}.$$

This implies the existence of $u^{(2m)}$ and the equality

$$(-1)^m u^{(2m)} = F^{(m)} = \varphi. \text{ And this means equality}$$

$$\mathcal{L}u = f,$$

where L is defined by (1.1). From (3.3) and (3.5)

$$(\forall v \in W_S) \sum_{i=1}^m (-1)^{i-1} u^{(m+i-1)} v^{(m-i)} \Big|_0^l = 0. \quad (3.8)$$

From here it follows (1.2).

One Generalization of Fubini's Theorem

For completeness of presentation and ease of reading, we present the transformation of the integral we need (see also [3]).

Lemma 3.11 ([11]). Let (X, \mathcal{A}) and (Y, \mathcal{B}) be measurable spaces, μ be a measure in (X, \mathcal{A}) , K colon $X \times B \rightarrow [0, \infty]$ is core (i.e. for μ -almost all $x \in X$ $K(x, \cdot)$ it is a measure in (Y, \mathcal{B}) , $\forall B \in \mathcal{B}$ $K(\cdot, B)$ is μ -measurable in X).

Then

1. the function ν defined in $A \times B$ by equality

$$\nu(E) = \int_X K(x, E_x) \mu(dx), \quad E_x = \{y : (x, y) \in E\},$$

is a measure,

2. if $f : X \times Y \rightarrow [-\infty, \infty]$ ν -measurable in $X \times Y$, then

$$\int_{X \times Y} f(x, y) d\nu = \int_X \left(\int_Y f(x, y) K(x, dy) \right) \mu(dx).$$

Remark 3.1. The function ν is a Lebesgue extension of the set of rectangles

$$\nu(A \times B) = \int_A K(x, B) \mu(dx), \quad A \in \mathcal{A}, B \in \mathcal{B},$$

Let us now apply this statement to our problem (in the notation of section 1.2). In our case $X = Y = \Delta$, the measure μ coincides with the Lebesgue measure.

Lemma 3.12. Let $f(x, y)$ be a ξ -measurable function. Under the assumptions of section 1.2 the following equality is valid:

$$\int_{\Delta \times \Delta} f(x, s) d\xi = \int_{\Delta} dx \int_{\Delta} f(x, s) r(x, ds). \quad (3.9)$$

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